

# DATASHEET

## Variable Speed Drives



### Main Features



Reference : CFW500E49P0T4DB20G2  
 Product code : 15577452  
 Product reference : CFW500 G2  
 Accessory module (control) : CFW500-IOS

### Basic data

Power supply : 380-480 V  
 Input minimum-maximum voltage : 323-528 V  
 Number of phases  
 - Input : 3  
 - Output : 3

Supply voltage range	380-480 V	
Overload cycle	Normal Overload (ND)	Heavy Overload (HD)
Rated current	58 A	49 A
Overload current for 60 sec	64,4 A	73,5 A
Overload current for 3 sec	87,8 A	98,0 A

Maximum applicable motor:

Voltage/Frequency	Power (HP/kW) [1]	
	Normal Overload (ND)	Heavy Overload (HD)
380V / 50Hz	Not applicable	30 / 22
380V / 60Hz	Not applicable	30 / 22
400V / 50Hz	Not applicable	30 / 22
400V / 60Hz	Not applicable	30 / 22
440V / 50Hz	Not applicable	30 / 22
440V / 60Hz	Not applicable	30 / 22
460V / 60Hz	Not applicable	40 / 30
480V / 60Hz	Not applicable	40 / 30

Accessory module (control) : CFW500-IOS  
 Dynamic braking [2] : Standard with braking  
 External electronic supply 24Vcc : Not available  
 Safety Stop : Prepared to use the safety module (G2)  
 Internal RFI filter : Without filter  
 External RFI filter : Not available  
 Link Inductor : No  
 Memory card : Not included in the product  
 USB port : Only with plug-in  
 Line frequency : 50/60Hz  
 Line frequency range (minimum - maximum) : 48-62 Hz  
 Phase unbalance : Less or equal to 3% of input rated line voltage  
 Transient voltage and overvoltage : Category III  
 Single-phase input current [3] : Not applicable  
 Three-phase input current [3] : 54,9 A  
 Typical input power factor : 0.75  
 Displacement factor : 0.98  
 Rated efficiency :  $\geq 97\%$   
 Maximum connections (power up cycles - on/off) per hour : 10 (1 each 6 minutes)  
 DC power supply : Allow  
 Standard switching frequency : 5 kHz  
 Selectable switching frequency : 2.5 and 15 kHz  
 Real-time clock : Not available  
 Copy Function : Yes, by MMF or plug-in or alphanumeric HMI  
 Dissipated power:

Mounting type	Overload	
	ND	HD
Surface	750 W	750 W
Flange	Not applicable	Not applicable

### Source available to the user

Output voltage : 24 Vcc  
 Maximum capacity : 150 mA

### Control/performance data

Power supply : Switched-mode power supply  
 Control method - induction motor : V/f, VVW, Sensorless, Encoder and VVW PM  
 Encoder interface : Only with plug-in  
 Control output frequency [5] : 0-500 Hz

### Control/performance data

Frequency resolution	: 0,015 Hz
V/F Control	
- Speed regulation	: 1% of rated speed
- Speed variation	: 1:20
VVW Control	
- Speed regulation	: 1% of rated speed
- Speed variation	: 1:30
Sensorless vector control	
- Speed regulation	: 0,5% of rated speed
- Speed variation	: 1:100
Vector control with Encoder	
- Speed regulation	: 0,1% of nominal speed
- Speed variation	: Up to 0 rpm

### Analog Inputs

Quantity (standard)	: 1
Levels	: 0-10V, 0-20mA and 4-20mA
Impedance for voltage input	: 100 k $\Omega$
Impedance for current input	: 500 $\Omega$
Function	: Programmable
Maximum allowed voltage	: 30 Vcc

### Digital inputs

Quantity (standard)	: 4
Activation	: Active low and high
Maximum low level	: 5 V (low) e 15 V (high)
Minimum high level	: 9 V (low) e 20 V (high)
Input current	: 4.5 mA
Maximum input current	: 5.5 mA
Function	: Programmable
Maximum allowed voltage	: 30 Vcc

### Analog outputs

Quantity (standard)	: 1
Levels	: 0 to 10V, 0 to 20mA and 4 to 20mA
RL for voltage output	: 10 k $\Omega$
RL for current output	: 500 $\Omega$
Function	: Programmable

### Digital outputs

Quantity (standard)	: 1 NO/NC relay and 1 transistor
Maximum voltage	: 240 Vca and 24 Vcc
Maximum current	: 0.5 A and 150 mA
Function	: Programmable

### Communication

- Modbus-RTU (with accessory: Any plug-in module)
- Modbus/TCP (with accessory CFW500-CEMB-TCP)
- Profibus DP (with accessory: CFW500-CPDP)
- Profibus DPV1 (with accessory: CFW500-CPDP)
- Profinet (with accessory CFW500-CEPN-IO)
- CANopen (with accessory: CFW500-CCAN)
- DeviceNet (with accessory: CFW500-CCAN)
- EtherNet/IP (with accessory CFW500-CETH-IP)
- EtherCAT (Not available)
- BACnet (CFW500 G2 / CFW501 G2 / MW500 G2 with accessory: Any plug-in module)

### Available protection

- Output phase-phase overcurrent/Short
- Overcurrent/Short circuit phase-ground
- Under/Overvoltage in power
- Heat sink overtemperature
- Motor overload
- IGBT's modules overload
- Fault/External alarm
- Programming error

### Operation interface (HMI)

Availability	: Included in the product
HMI installation	: Fixed HMI
Number of HMI buttons	: 9
Display	: Numeric LCD
Indication accuracy	: 5% of rated current

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### Operation interface (HMI)

Speed resolution : 0,1 Hz  
 Standard HMI degree of protection : IP20  
 HMI battery type : Not applicable  
 HMI battery life expectancy : Not applicable  
 Remote HMI type : Accessory  
 Remote HMI frame : Not applicable  
 Remote HMI degree of protection : IP54

### Ambient conditions

Enclosure : IP20  
 Pollution degree : 2 (EN50178 and UL508C)  
 Temperature around the inverter: of -10 °C / 14 °F to 50 °C / 122 °F. For temperatures above the specified is necessary to apply current reduction of 2 % per °C of 50 (122) o 60 °C (140 °F).  
 Relative humidity: 5% to 95% without condensation.  
 Altitude: up to 1000 m (3281 ft) under normal conditions. Of 1000 m (3281 ft) to 4000 m (13123 ft) reduce the current in 1% for each 100 m above (0,3% for each 100 ft above) of 1000 m (3281 ft). Reduce the maximum voltage (240 V for models 200...240 V, 480 V for models 380...480 V and 600 V for models 500...600 V) in 1,1% for each 100 m above (0,33% for each 100 ft above) of 2000 m.

### Sustainability policies

RoHS : Yes  
 Conformal Coating : 3C2 (IEC 60721-3-3:2002)

### Dimensions and weight

- Size : E  
 - Height : 350 mm / 13.8 in  
 - Width : 220 mm / 8.66 in  
 - Depth : 191.5 mm / 7.5 in  
 - Weight : 10 kg / 22 lb

### Mechanical Installation

Mounting position : Surface  
 Fixing screw : M6  
 Tightening torque : 4.5 N.m / 3.32 lb.ft  
 Allows side-by-side assembly : No  
 Minimum spacing around the inverter:  
 - Top : 110 mm / 4.33 in  
 - Bottom : 130 mm / 5.12 in  
 - Front : 50 mm / 1.97 in  
 - Between inverters (IP20) : 40 mm / 1.57 in

### Electrical connections

Cable gauges and tightening torques:

	Recommended cable gauge	Recommended tightening torque
Power	16.0 mm <sup>2</sup> (4 AWG)	3.05 N.m / 2.2 lb.ft
Braking	10.0 mm <sup>2</sup> (8 AWG)	3.05 N.m / 2.2 lb.ft
Grounding	16.0 mm <sup>2</sup> (4 AWG)	0.5 N.m / 0.37 lb.ft
Control	0.5 to 1.5 mm <sup>2</sup> (20 to 14 AWG)	0,5 N.m / 0.37 lb.ft

SoftPLC : Yes, incorporated  
 Maximum breaking current : 78.0 A  
 Minimum resistance for the brake resistor : 8.6 Ω  
 Recommended aR fuse [6] : FNH00-100K-A  
 Recommended circuit breaker [6] : MPW80i-3-U065  
 Disconnect switch : Not applicable  
 Motor coupling box : Not applicable

### Standards

Safety	<ul style="list-style-type: none"> <li>- UL 508C - Power conversion equipment.</li> <li>- UL 840 - Insulation coordination including clearances and creepage distances for electrical equipment.</li> <li>- EN 61800-5-1 - Safety requirements electrical, thermal and energy.</li> <li>- EN 50178 - Electronic equipment for use in power installations.</li> <li>- EN 60204-1-Safety of machinery. Electrical equipment of machines. Part 1: General requirements. Note: To have a machine in accordance with that standard, the manufacturer of the machine is responsible for the installation of an emergency-stop device and a network switching equipment.</li> <li>- EN 60146 (IEC 146) - Semiconductor converters.</li> <li>- EN 61800-2 - Adjustable speed electrical power drive systems - Part 2: General requirements - Rating specifications for low voltage adjustable frequency AC power drive systems.</li> </ul>
Electromagnetic Compatibility	<ul style="list-style-type: none"> <li>- EN 61800-3 - Adjustable speed electrical power drive systems - Part 3: EMC product standard including specific test methods.</li> <li>- EN 55011 - Limits and methods of measurement of radio disturbance characteristics of industrial, scientific and medical (ISM) radio-frequency equipment.</li> </ul>



### Standards

	<ul style="list-style-type: none"> <li>- CISPR 11 - Industrial, scientific and medical (ISM) radio-frequency equipment</li> <li>- Electromagnetic disturbance characteristics - Limits and methods of measurement.</li> <li>- EN 61000-4-2 - Electromagnetic compatibility (EMC) - Part 4: Testing and measurement techniques - Section 2: Electrostatic discharge immunity test.</li> <li>- EN 61000-4-3 - Electromagnetic compatibility (EMC) - Part 4: Testing and measurement techniques - Section 3: Radiated, radio-frequency, electromagnetic field immunity test.</li> <li>- EN 61000-4-4 - Electromagnetic compatibility (EMC) - Part 4: Testing and measurement techniques - Section 4: Electrical fast transient/burst immunity test.</li> <li>- EN 61000-4-5 - Electromagnetic compatibility (EMC) - Part 4: Testing and measurement techniques - Section 5: Surge immunity test.</li> <li>- EN 61000-4-6 - Electromagnetic compatibility (EMC)- Part 4: Testing and measurement techniques - Section 6: Immunity to conducted disturbances, induced by radio-frequency fields.</li> </ul>
Mechanical Construction	<ul style="list-style-type: none"> <li>- EN 60529 - degrees of protection provided by enclosures (IP code).</li> <li>- UL 50 - enclosures for electrical equipment.</li> <li>- IEC 60721-3-3 - classification of environmental conditions - part 3: classification of groups of environmental parameters and their severities - section 3: stationary use at weather protected locations level 3m4.</li> </ul>

### Certifications

UL, CE, RCM, CS/IRAM, EAC, UKCA and RoHS  
CHINA

### Notes

- 1) Motor power is orientative, valid for standard WEG Motors of IV poles. The correct sizing must be done according to the nominal current of the motor used, which must be less than or equal to the rated output current of the inverter;
- 2) Braking resistor is not included;
- 3) Considering minimum line impedance of 1%;
- 4) For more information, refer to the user manual of CFW500 G2;
- 5) All images are merely illustrative.
- 6) For operation with switching frequency above nominal, apply derating to the output current (refer to the user manual).